

# MPACT Overview

February 11, 2019

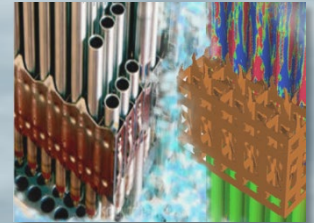
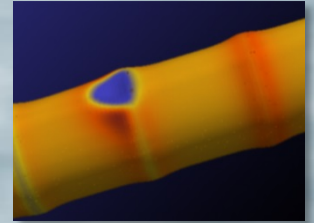
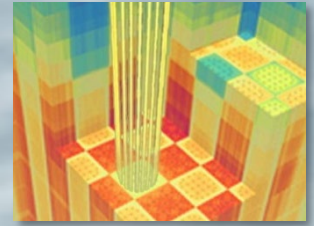
VERA Workshop

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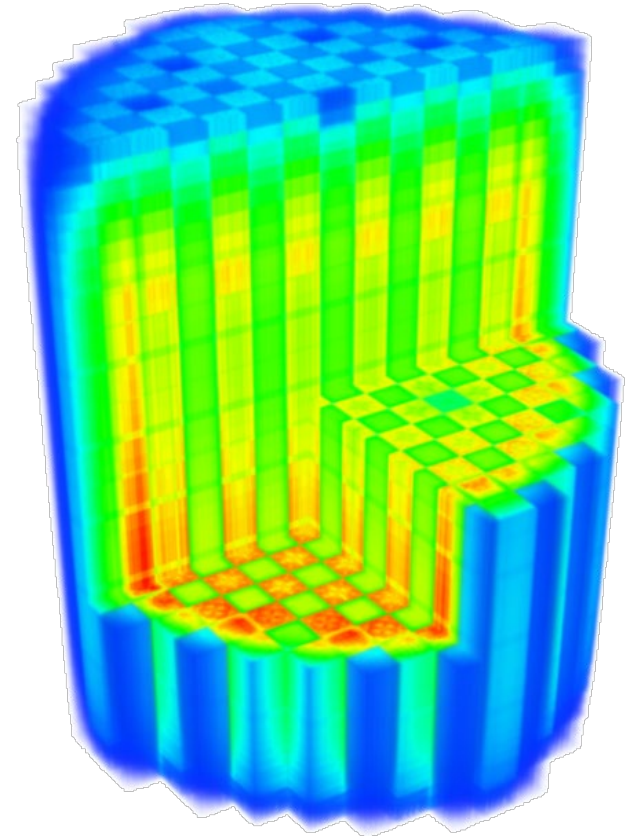
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# Outline

- Background
- 2D/1D Method
  - Radial and Axial Equations
  - Coarse Mesh Finite Difference
- Parallel Decomposition Approach
- XS Library Background
- Depletion/Shuffling
- Reflector Fidelity
- Transient Capability



AP1000 HFP Power Distribution

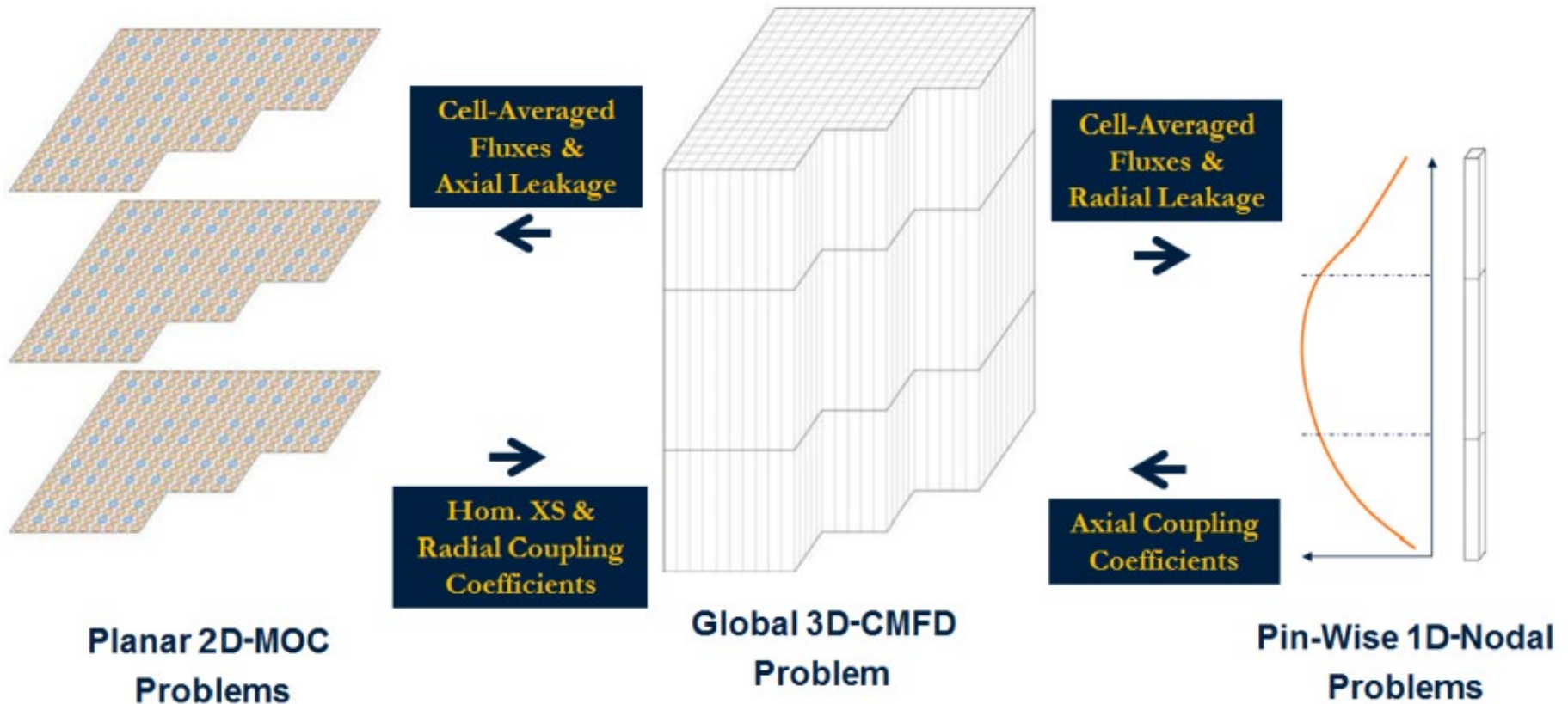
# Background

- MPACT is a deterministic transport solver package that originally began development exclusively at the University of Michigan (~2011)
- Since 2014, development has been collaboratively driven by both ORNL and Michigan
- Goal to provide high-fidelity, pin-resolved flux and power distributions
- Several solvers are available, but the workhorse is the 2D/1D method
  - Decomposes 3D problems into an axial stack of radial planes
  - 2D-MOC used radially, and 1D-nodal methods used axially
  - Accelerated with 3D-coarse mesh finite difference (CMFD)

# Comparison to Industry Neutronics Tools

Physics Model	Industry Practice	CASL (VERA-CS)
<b>Neutron Transport</b>	3-D diffusion (core) 2 energy groups (core) 2-D transport on single assy	3-D transport 51+ energy groups
<b>Power Distribution</b>	nodal average with pin-power reconstruction methods	explicit pin-by-pin
<b>Xenon/Samarium</b>	nodal average w/correction	pin-by-pin
<b>Depletion</b>	infinite-medium cross sections quadratic burnup correction history corrections spectral corrections reconstructed pin exposures	pin-by-pin with actual core conditions
<b>Reflector Models</b>	1-D cross section models	actual 3-D geometry
<b>Target Platforms</b>	workstation (single-core)	1,000 – 100,000 cores

# 2D/1D Illustration



# Radial Equations

- Axially-Averaged Transport:  $\varphi_{g,l}^Z(x, y) = \frac{1}{h_z} \int_{z_B}^{z_T} \varphi_{g,l}(x, y, z) dz$ 
  - $\mu_l$  denotes cosine of polar angle
  - $\alpha_l$  denotes azimuthal angle

$$\sqrt{1 - \mu_l^2} \left( \cos(\alpha_l) \frac{\partial}{\partial x} + \sin(\alpha_l) \frac{\partial}{\partial y} \right) \varphi_{g,l}^Z(x, y) + \Sigma_{t,g}^Z(x, y) \varphi_{g,l}^Z(x, y) = \tilde{q}_{g,l}^Z(x, y)$$

$$\tilde{q}_{g,l}^Z(x, y) = \bar{q}_{g,l}^Z(x, y) + TL_{g,l}^Z(x, y) \quad \leftarrow \text{Axial Transverse Leakage}$$

$$TL_{g,l}^Z(x, y) = \frac{\mu_l}{h_z} \left( \varphi_{B,g,l}(x, y) - \varphi_{T,g,l}(x, y) \right)$$

# Axial TL - Approximations

- Isotropic Approximation:

$$TL_{g,l}^Z(x, y) = \frac{J_{B,g}(x, y) - J_{T,g}(x, y)}{4\pi h_z}$$

- Flat Approximation:

$$TL_{g,l}^Z(x, y) = \frac{J_{B,g}^{XY} - J_{T,g}^{XY}}{4\pi h_z}$$

# Method of Characteristics

- MOC is used to discretize the 2D transport equation and determine subpin level angular and scalar fluxes:

$$\boldsymbol{\Omega} \cdot \nabla \varphi(x, y) + \Sigma_t(x, y)\varphi(x, y) = Q(x, y)$$

- Casting this along a characteristic direction:

- Can convert PDE into ODE

- Assuming step characteristics:  $\frac{d\varphi}{ds} + \Sigma_t\varphi(s) = Q$

- The angular flux at any point  $s$  along this direction can be found:

$$\varphi(s) = \varphi_{in}e^{-\Sigma_t s} + \frac{Q}{\Sigma_t}(1 - e^{-\Sigma_t s}), \quad \varphi(0) = \varphi_{in}$$



# Method of Characteristics

- Outgoing Angular Flux:

$$\varphi_{out,m} = \varphi(s = l_m) = \varphi_{in,m} e^{-\Sigma_t l_m} + \frac{Q}{\Sigma_t} (1 - e^{-\Sigma_t l_m}), \quad l_m = t / \sin(\theta_m)$$

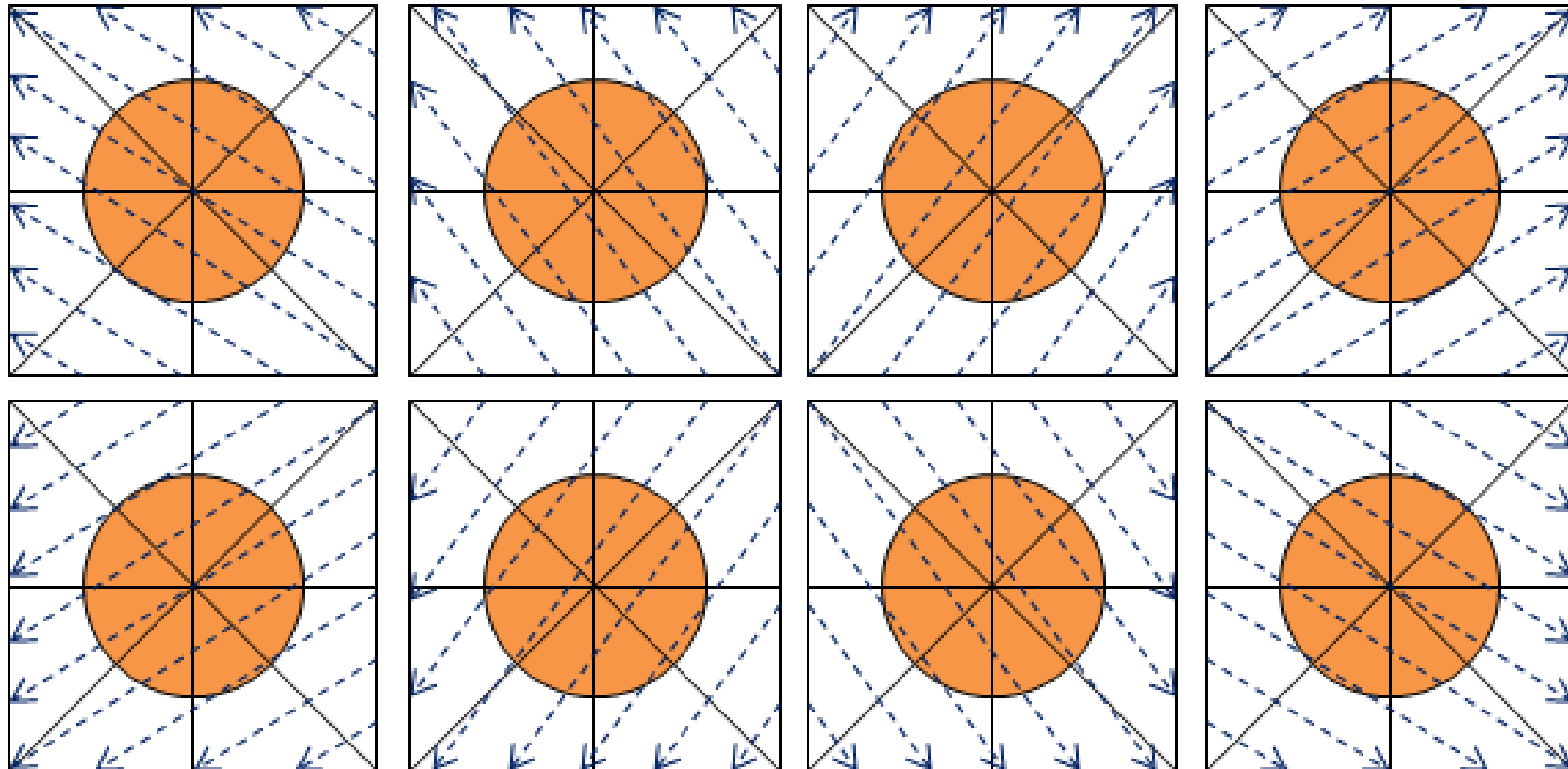
- Average Angular Flux along a segment:

$$\tilde{\varphi}_m = \frac{1}{l_m} \int_0^{l_m} \varphi(s) ds = \frac{Q}{\Sigma_t} + \frac{\varphi_{in,m} - \varphi_{out,m}}{\Sigma_t l_m}$$

- Scalar flux within a region:

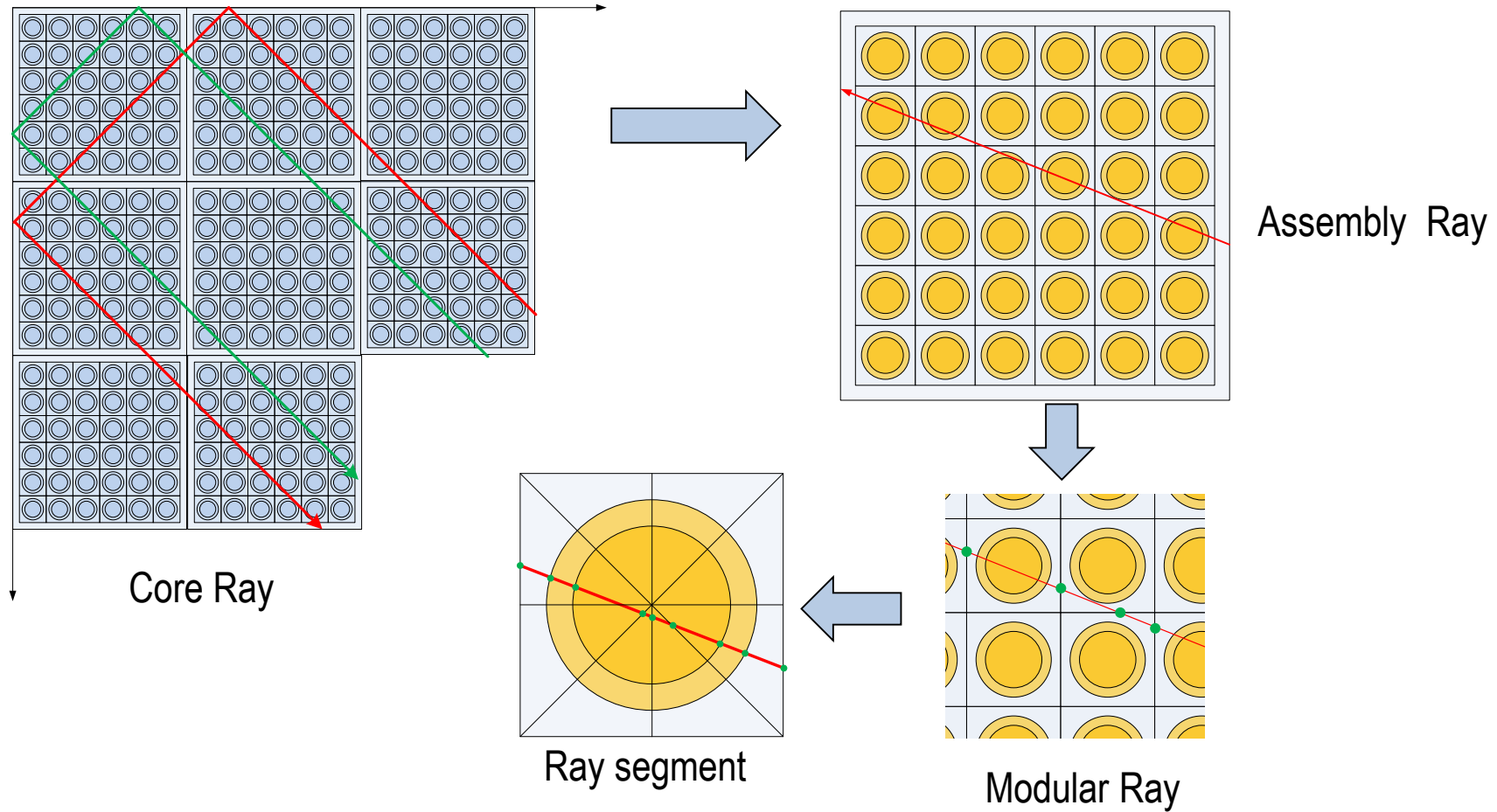
$$\bar{\varphi}_l = \frac{\sum_{r=1}^{N_{ray,l}} \delta_r l_r \tilde{\varphi}_{l,r}}{\sum_{r=1}^{N_{ray,l}} \delta_r l_{m,r}}, \quad \bar{\phi} = \sum_{i=1}^{N_{ang}} w_i \bar{\varphi}_l$$

# Method of Characteristics



- 16 regions, 8 azimuthal angles,

# Modular Ray Tracing



# Axial Equations

- Radially-Averaged Transport:

$$\varphi_{g,l}^{XY}(z) = \frac{1}{A_{xy}} \int_{y_L}^{y_R} \int_{x_L}^{x_R} \varphi_{g,l}(x, y, z) dx dy$$

$$\mu_l \frac{\partial}{\partial z} \varphi_{g,l}^{XY}(z) + \Sigma_{t,g}^{XY}(z) \varphi_{g,l}^{XY}(z) = \tilde{q}_{g,l}^{XY}(z)$$

$$\tilde{q}_{g,l}^{XY}(z) = \bar{q}_{g,l}^{XY}(z) + TL_{g,l}^{XY}(z)$$

← Radial Transverse Leakage

- Total/transport cross section homogenized with scalar flux
- Diffusion approximation can be made for some solvers

# Axial Equation

- In explicit form:
  - $\mu_l$  denotes cosine of polar angle
  - $\alpha_l$  denotes azimuthal angle

$$TL_{g,l}^{XY}(z) = -\frac{\sqrt{1-\mu_l^2}}{A_{xy}} \left( \begin{array}{l} \cos(\alpha_l) \int_{y_L}^{y_R} (\varphi_{g,l}(x_R, y, z) - \varphi_{g,l}(x_L, y, z)) dy \\ + \sin(\alpha_l) \int_{x_L}^{x_R} (\varphi_{g,l}(x, y_R, z) - \varphi_{g,l}(x, y_L, z)) dx \end{array} \right)$$

- Isotropic:

$$TL_{g,l}^{XY}(z) = \frac{1}{4\pi h_x} (J_{L,x,g}(z) - J_{R,x,g}(z)) + \frac{1}{4\pi h_y} (J_{L,y,g}(z) - J_{R,y,g}(z))$$

- And Flat:

$$TL_{g,l}^{XY}(z) = \frac{1}{4\pi h_x} (J_{L,x,g}^Z - J_{R,x,g}^Z) + \frac{1}{4\pi h_y} (J_{L,y,g}^Z - J_{R,y,g}^Z)$$

# Axial Transport Solver

- 1D  $P_N$

- Uses an  $N^{\text{th}}$  order polar expansion for the angular flux:

$$\varphi_g(z, \mu) = \sum_{m=0}^{N_{mom}} \frac{2m+1}{2} \varphi_{m,g}(z) P_m(\mu)$$

- Wraps one-node NEM (4<sup>th</sup> order Legendre expansion) kernel for spatial representation

- NEM- $P_3$ :

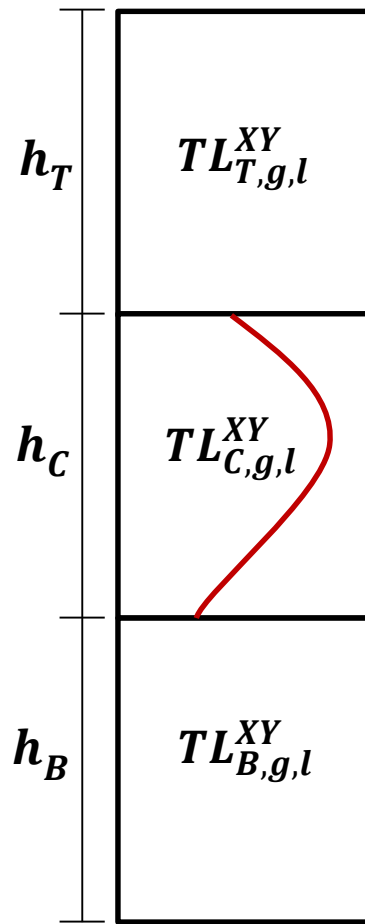
$$-\frac{4D_{0,g}}{h^2} \frac{d^2}{d\xi} \Phi_{0,g}(\xi) + \Sigma_{r,g} \Phi_{0,g}(\xi) = Q_g(\xi) + 2\Sigma_{r,g} \Phi_{2,g}(\xi)$$

$$-\frac{4D_{2,g}}{h^2} \frac{d^2}{d\xi} \Phi_{2,g}(\xi) + \left( \Sigma_{t,g} + \frac{4}{5} \Sigma_{r,g} \right) \Phi_{2,g}(\xi) = -\frac{2}{5} \left( Q_g(\xi) - \Sigma_{r,g} \Phi_{0,g}(\xi) \right)$$

$$D_{0,g} = \frac{1}{3\Sigma_{tr,g}}$$

$$D_{2,g} = \frac{9}{35\Sigma_{t,g}}$$

# Radial TL Interpolation



- The currents used to generate the radial transverse leakages do not have axial dependence
- To compensate for this, a quadratic expansion for the leakage is formulated:

$$TL_{g,l}^{XY}(\xi) = \sum_{i=0}^2 TL_{g,l,i}^{XY} P_i(\xi)$$

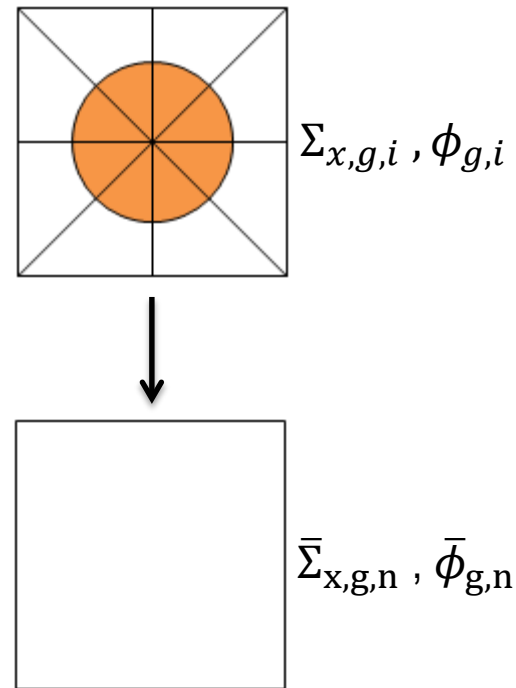
- Uses information from the upper and lower neighboring planes

# Coarse Mesh Finite Difference

- CMFD is used as an accelerator to improve eigenvalue and scalar flux convergence in a wide range of transport solvers
- Pin-wise coarse cells
- Homogenization:

$$\bar{\Sigma}_{x,g,n} = \frac{\sum_{i \in n} \Sigma_{x,g,i} V_i \phi_{g,i}}{\sum_{i \in n} V_i \phi_{g,i}}, \quad \bar{\phi}_{g,n} = \frac{\sum_{i \in n} V_i \phi_{g,i}}{\sum_{i \in n} V_i}$$

- Projection:  $\bar{\xi}_{g,i,n} = \frac{\phi_{g,i}}{\bar{\phi}_{g,n}}$





# Coarse Mesh Finite Difference

- To perform a CMFD iteration, coupling coefficients are formulated:
  - Finite difference coupling coefficient:

$$\tilde{D}_{g,n,i} = \frac{2D_{g,n}D_{g,n(i)}}{D_{g,n}h_{n(i),i} + D_{g,n(i)}h_{n,i}}$$

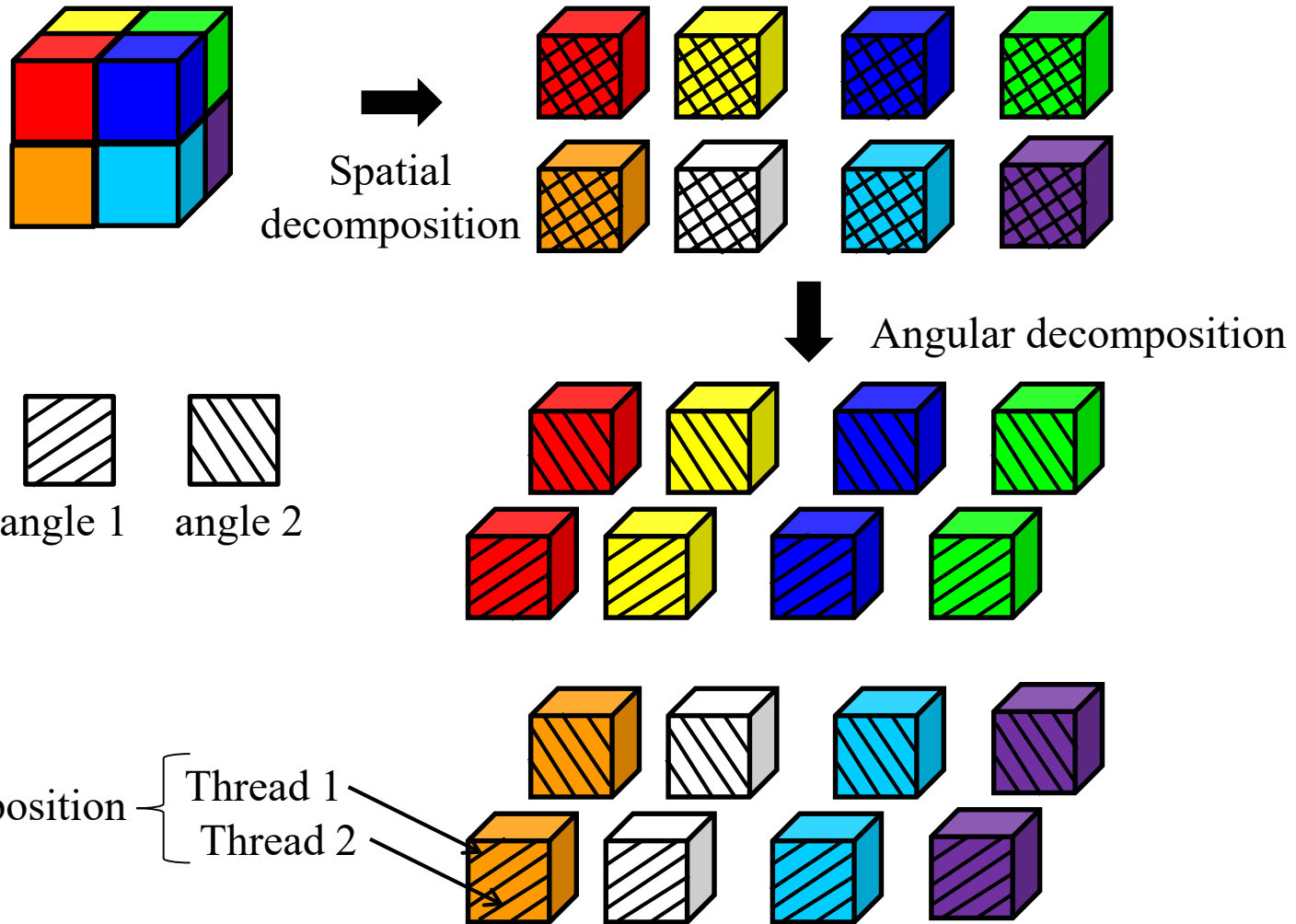
- Current correction coupling coefficient

$$J_{s,g,n,i}^{transport} = -\tilde{D}_{g,n,i}(\phi_{g,n} - \phi_{g,n(i)}) + \hat{D}_{g,n,i}(\phi_{g,n} + \phi_{g,n(i)})$$

$$\hat{D}_{g,n,i} = \frac{J_{s,g,n,i}^{transport} + \tilde{D}_{g,n,i}(\phi_{g,n} - \phi_{g,n(i)})}{\phi_{g,n} + \phi_{g,n(i)}}$$

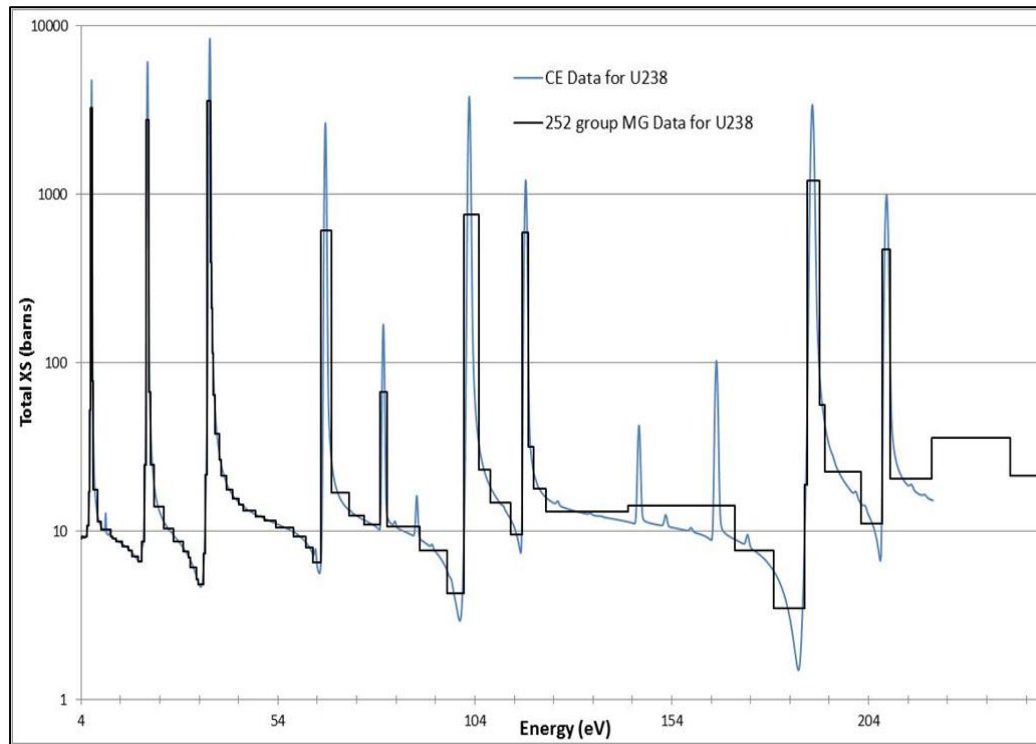
- Constructs and solves an  $n\text{Cell} \times n\text{Cell} \times n\text{Group}$  matrix

# Parallel Decomposition



# XS Libraries and Scattering

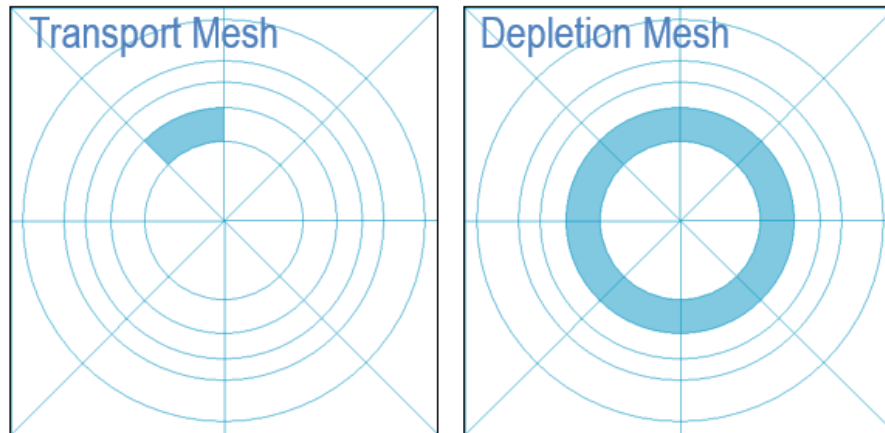
- ENDF-B/VII basic nuclear data library
  - Collapsed to a multi-group library (51/252 groups)
  - Library generated with SCALE codes



- Subgroup Resonance Self Shielding
- Default  $TCP_0$  scattering ( $P_N$  available)

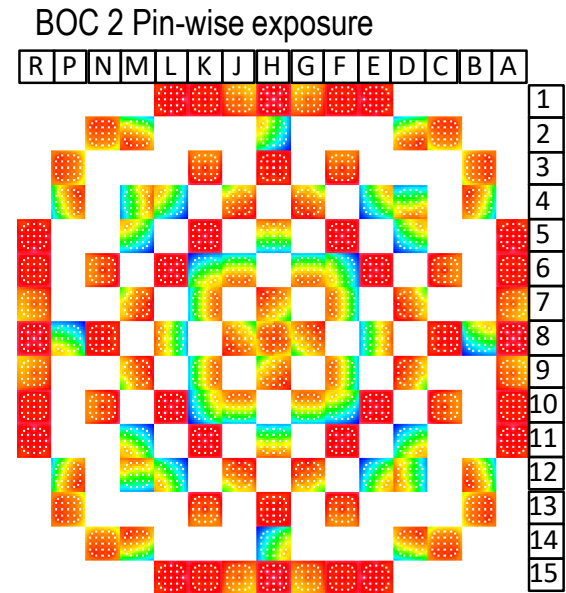
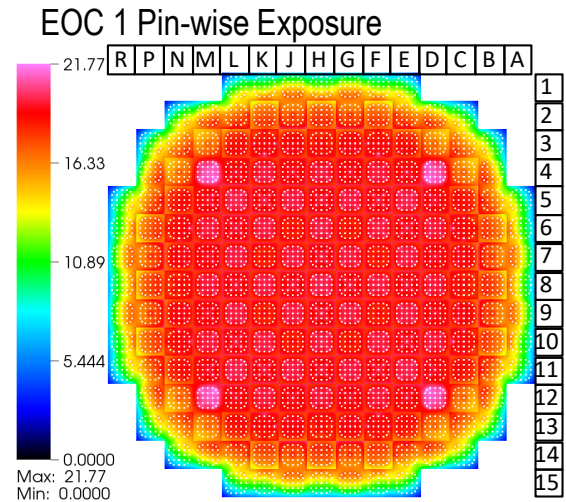
# Depletion Methodology through ORIGEN

- Over 40 years of applications and validation bases within SCALE
- In-line depletion and decay of the fuel and burnable poisons
- Includes capability for activity, decay heat, radiation emission rates, and activation of structural materials
- Reduced isotope chain developed to improve run time and memory footprint
  - ~2200 → 263 isotopes

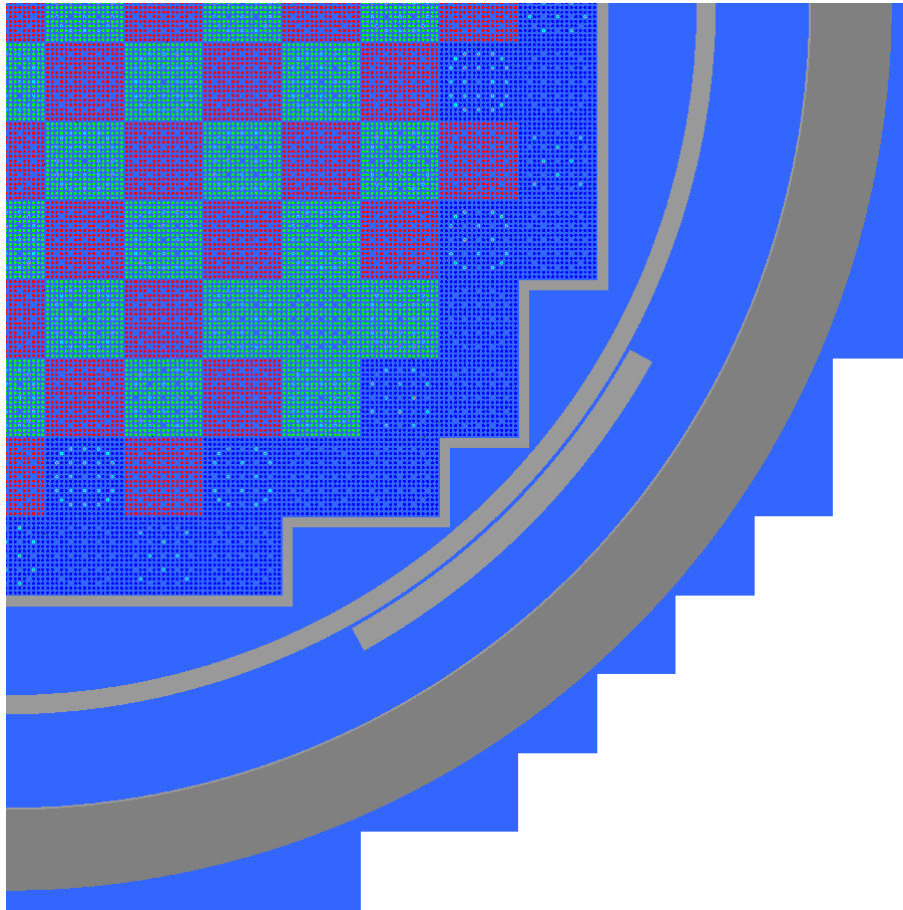


# Fuel Shuffling Capability

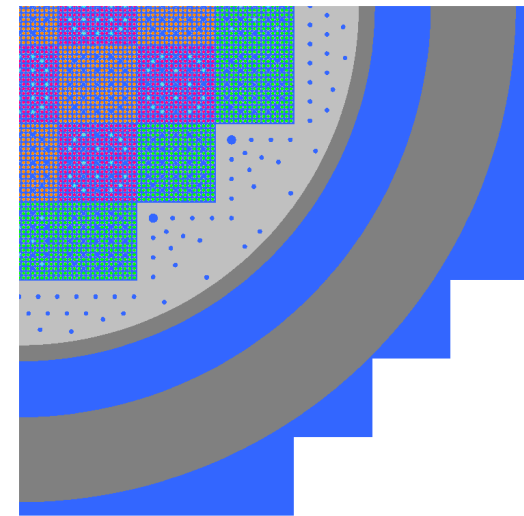
- Depletion and fuel shuffle capability
  - Tracks isotopic transmutation in every region
  - Stores exact isotopics for entire core
  - Provides mechanism to shuffle full core correctly rotating isotopics
  - Decays all isotopes over outage
- Also manages shuffling and restart data for multiphysics calculations
  - CRUD restart information from MAMBA
  - Vessel fluence restart data from Shift
  - CTFFuel restart data



# Reflector/Vessel Resolution



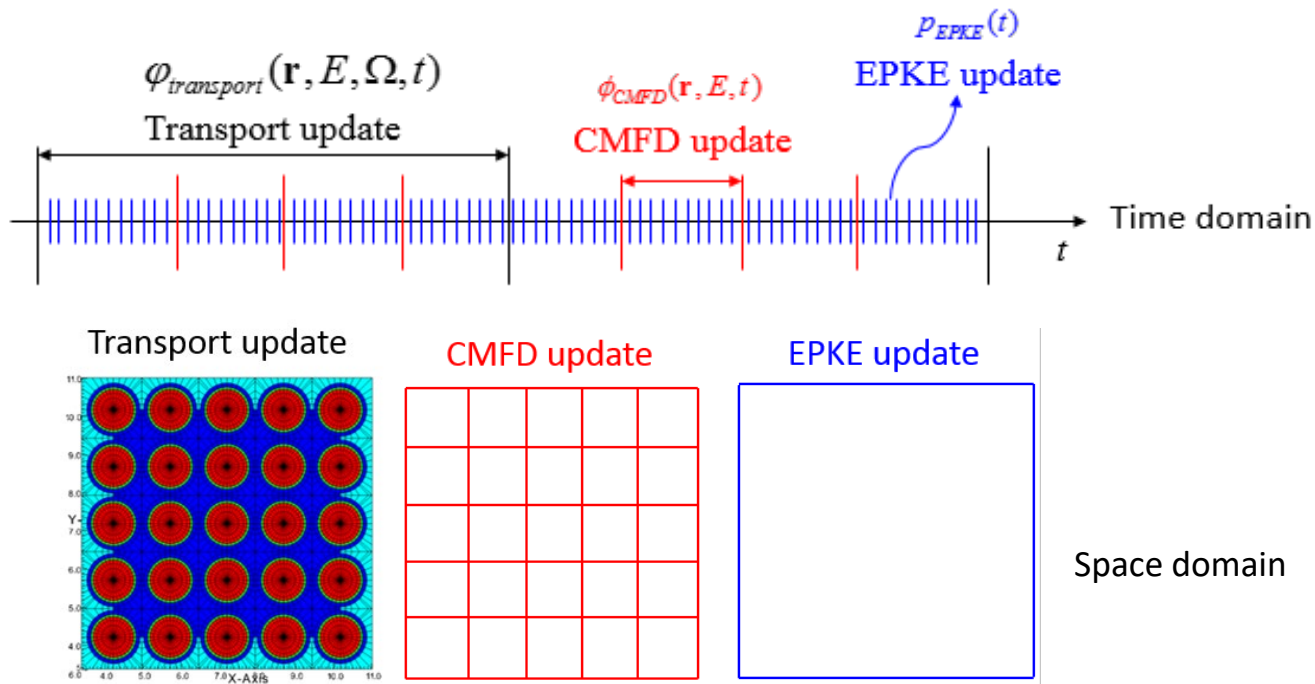
Watts Bar Unit 1 Slice



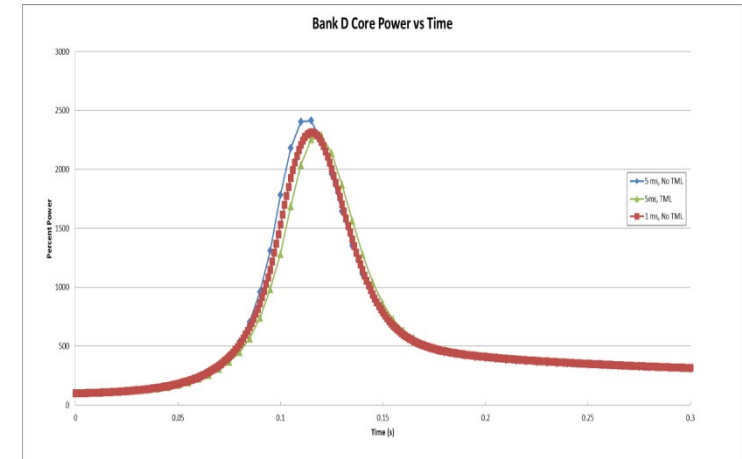
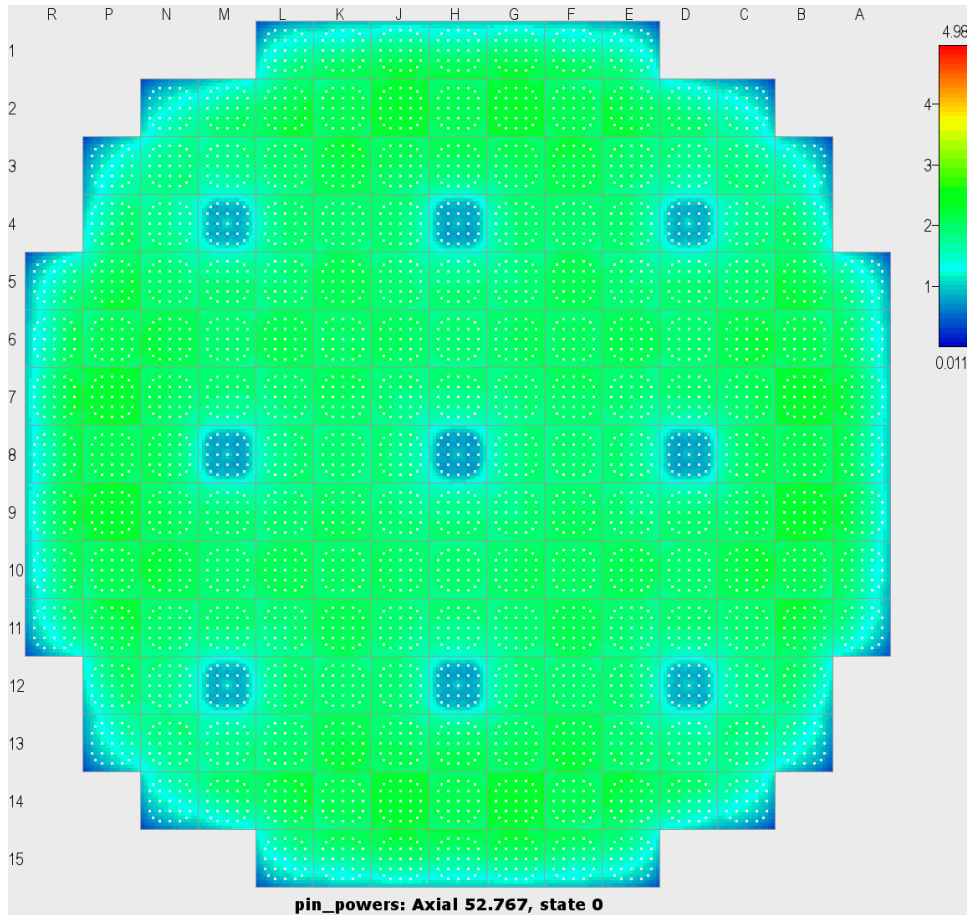
NuScale-like Slice

# Transient Multi-level (TML) Method

- Pure transport transient calculation is computationally very expensive.
- Objective of the TML method is to use multi-level transient solvers to capture the physical phenomena in different time domains to maximize the numerical accuracy and computational efficiency.



# Transient Application to Watts Bar



Time Step	TML Enabled	Runtime
1 ms	No	8.7 hours
5 ms	No	2.3 hours
5 ms	Yes	3.3 hours



# Summary

- Reviewed the 2D/1D equations
  - Approximations to Transport Equation
  - MOC,  $P_3$ , CMFD
  - Leakage Approximations
- Other key components
  - Depletion, Shuffling, Parallelization, XS Library
- Demonstrated transient capabilities
  
- Other MPACT capabilities are covered in later talks

# Questions?